Venetian Blind Wi－Fi Motor

User Manual


Models $\&$ Parameters（more info please refer to the nameplate）



## 03 Power Options



## 04 Caution！！

2．Power supply：adapter 12V／2A，power box 12V／1 A．
 4．During operation，the effective interval of the transmitter button operation is 10 second If there is no effective transmitter operation for more than 10 seconds，it will automatically exit the current mode．
5．The motor can be paired with max 10 controllers
6．Upper\＆Lower limits cannot be set at the same position，linits saved even power of
8．Do not lift the motor by grabbing and pull with thut any other operation．

| 05 Instructions |  |  |  |
| :---: | :---: | :---: | :---: |
| Paring Button functions |  |  |  |
| Functions | Operation | Jogging time | Note |
| Control the UP／STOP／ DOWN of the shade | Short press | 1 | It should be used when limits being set |
| Adding／Removing Controller | Hold for 2 s | Jog＊1 | Operation needs be done within |
| RF Control Inactive | Hold for 6 s | Jog＊2 |  control is inactive： Hold Pairing butuon for $2 s$, the $F F$ control is active again |
| Direction Reverse | Hold for 10 s | Jog ${ }^{3}$ | All settings saved after <br> ection reversed |
| Reset | Hold for 16s | jog＊ | All settings deleted |

## a．Pairing Motor with Control

Way 1：Before adding a new controller

Way 2：Ater motor is powered on for more than 10 s

Way 3 ：Power on，add controler $B$ via pre－existing controller
$\underset{\text { Press Prg on } \mathrm{A}}{\rightarrow} \rightarrow \underset{\text { Prog } \times 1}{\rightarrow} \rightarrow \square$
$\Rightarrow \operatorname{Jog}^{2} \rightarrow$ OK
te：Pairing can not be done under group channel or 0 channe

$$
\begin{aligned}
& \text {.Direction Reverse } \\
& \text { 不 } \Rightarrow \text { orrect } \rightarrow \\
& \text { Up Shade goes up Down Shade goes down } \\
& \text { If the limits are not set, and direction goes opposite. } \\
& \underset{\text { Fav \& Stop } \times 2 \mathrm{~s}}{\mathrm{C}} \& \underset{\mathrm{Jog} \times 1}{\square} \Rightarrow \text { Direction reversed } \\
& \text { Simits are set and diection }
\end{aligned}
$$

$$
\begin{aligned}
& \xrightarrow{\mathrm{Prg}} \mathrm{OK}
\end{aligned}
$$

Note：Do reverse the direction when it goes opposite，
c．UppersLower Limits Setting
不 or 业 $\Rightarrow$ 不\＆（ $\rightarrow$ 禺 $\rightarrow$
Up or Down Fix upper point Up \＆Fav x2s Jog x2 Upper
$\underset{\text { Up or Down }}{\text { 不 or }} \underset{\text { Fix lower point }}{\boldsymbol{p}} \rightarrow \underset{\text { Down \＆Fav } \times 2 \mathrm{~s}}{\boldsymbol{y}} \& \odot \underbrace{}_{\text {Jog } \times 2} \rightarrow \underset{\substack{\text { Lower } \\ \text { limit set }}}{\infty}$
Note：UpperkLower limits cannot be set at the same point．
Before linits set，the motor wil run in one－touch mode by pressing Up or Dow hold Up or Down for $2 s$ ，motor runs in constant－touch mode．
Once limits set，press Up or Down，motor runs in constant－touch
mo

## d．One－touch／Constant－touch Mode


Same operation can toggle from one touch to constant－touch mode．
Note：When motor in one－touch mode，hold Up or Down for more than 2 s，it will run is
constant－touch mode．

$\underset{\substack{\text { Shade is at } \\ \text { Fav．position }}}{\text { Canceling }} \rightarrow \underset{\text { Fav \＆Stop } \times 2 \text { s }}{\square} \rightarrow \underset{\text { Jog } \times 1}{\square} \rightarrow \underset{\substack{\text { Fav．Position } \\ \text { Cancel }}}{ }$

## f．Hot key to the Fav．Position

（C）$\Rightarrow$ fast get to the Fav．poin
Note：The Fav．position setting only can be done alter upperklower limits set．

## g.Adjusting Upper \& Lower Limits



$\rightarrow \underset{\mathrm{Jog} \times 2}{ } \rightarrow \mathrm{OK}$
Note: The operation should be done within 4 mins.


Note: If motor doesn't jog, the max/min speed has arready been reached.

## i.Removing Controllers

Remove a single controlle

$$
\begin{aligned}
& \text { buttonx2s }
\end{aligned}
$$



Method 2: Short Press Prg on back of controller, motor jogs once: short press Down,
motor jogs once, then short press UP, motor jogs once and blue indicator blinks which means motore enters WW-Fi-i connection statusus.
 d. Click "+" in the upper right corner of the APP, then click "Auto Scan", the APP will

e. Click "Next" when you find the device, enter the Wi-Fi account password and click

f. Atter adding device successfully, tap " $\langle$ " after the device name to modify the device
name.

g. The Wi-Fi module indicator is always on after succeesstul network connection.

h. Enter the main interface to control the operation of the venetian blind.


